

# Shadows

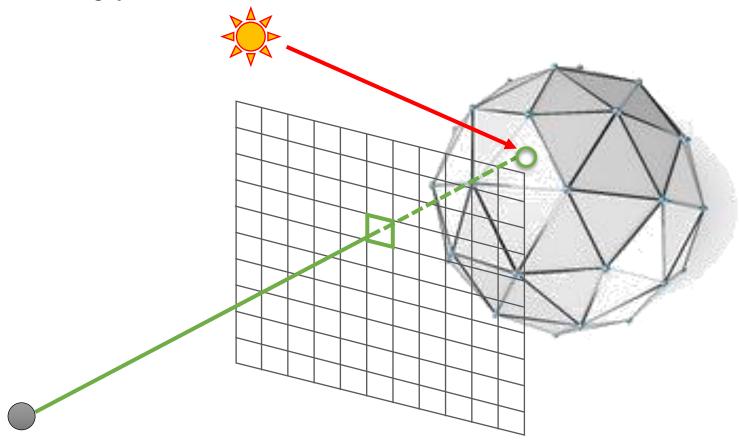
# **Computer Graphics**

Yu-Ting Wu

### **Shadow Map**

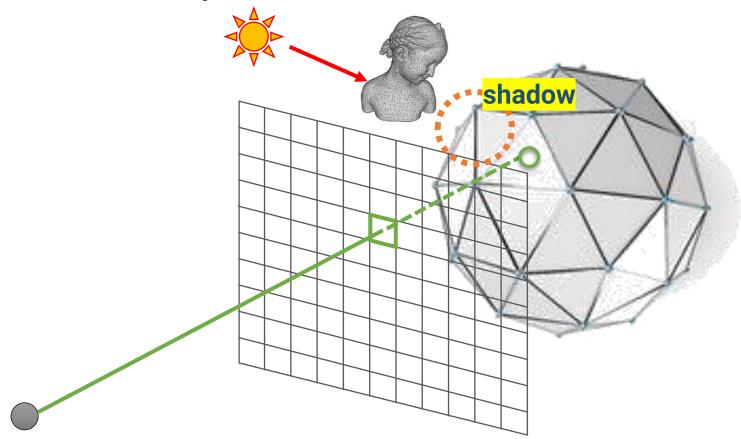
### Shadow

 So far, we consider the light to be fully visible to a shading point



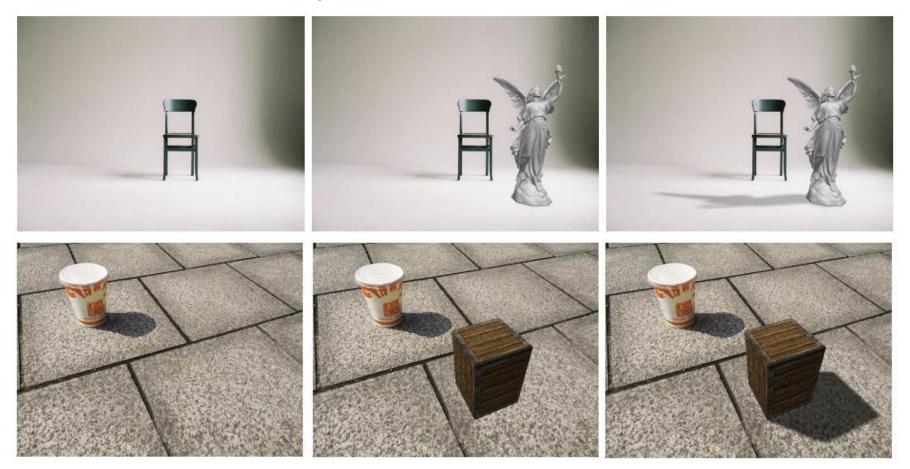
# Shadow (cont.)

 It is common that a lighting direction is occluded by some other objects



# Shadow (cont.)

• Shadows are very important to provide depth cues

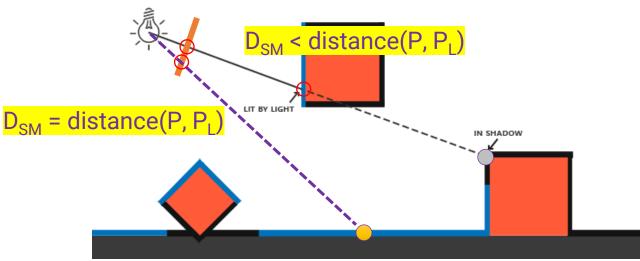


### **Shadow Map Overview**

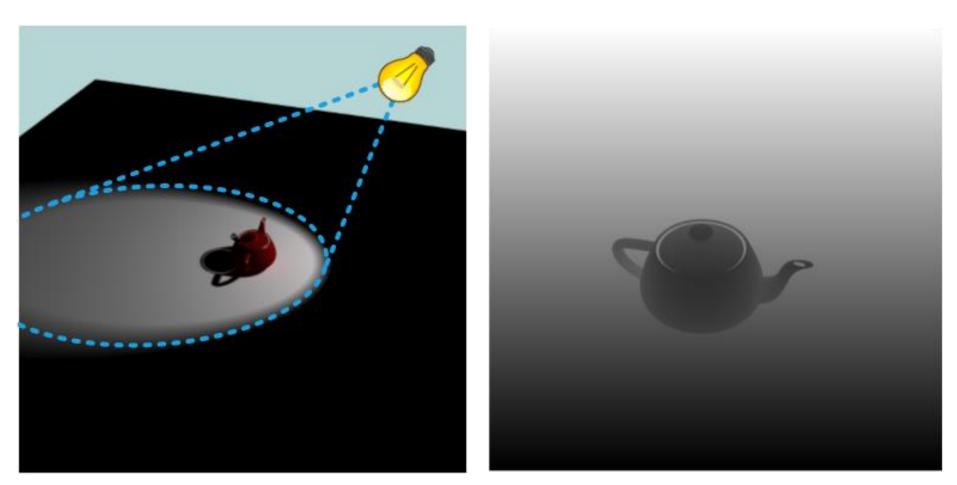
- Like the case of transparency, rendering shadows is difficult for rasterization because each polygon only has its own information
  - It does not know which triangle blocks the light, so it cannot determine the shadow attenuation in its fragment shader
- Shadow map is a two-pass rendering technique for simulating shadows using rasterization

# Shadow Map Overview (cont.)

- Major concept
  - First pass: rendering a depth map from the light position
    - Record the closest surface from the light and generate a shadow map
  - Second pass: rendering from the camera
    - During lighting computation, lookup the shadow map to determine the shadow



### Shadow Map Overview (cont.)



shadow map (rendering from the light view)

# Shadow Map Overview (cont.)

- Major concept
  - <u>https://learnopengl.com/Advanced-Lighting/Shadows/Shadow-Mapping</u>

rendering from the light view

```
// 1. first render to depth map
glViewport(0, 0, SHADOW_WIDTH, SHADOW_HEIGHT);
glBindFramebuffer(GL_FRAMEBUFFER, depthMapFBO);
    glClear(GL_DEPTH_BUFFER_BIT);
    ConfigureShaderAndMatrices();
    RenderScene();
glBindFramebuffer(GL_FRAMEBUFFER, 0);
// 2. then render scene as normal with shadow mapping (using depth map)
glViewport(0, 0, SCR_WIDTH, SCR_HEIGHT);
glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
ConfigureShaderAndMatrices();
glBindTexture(GL_TEXTURE_2D, depthMap);
RenderScene();
```

rendering from the camera view

# Shadow Map for Directional Lights

First pass: shadow map generation

rendering from the light view

<pre>// 1. first render to depth map glViewport(0, 0, SHADOW_WIDTH, SHADOW_HEIGHT); glBindFramebuffer(GL_FRAMEBUFFER, depthMapFBO); glClear(GL_DEPTH_BUFFER_BIT); ConfigureShaderAndMatrices(); rendering from the light view RenderScene(); glBindFramebuffer(GL_FRAMEBUFFER, 0); bind to default screen</pre>
<pre>// 2. then render scene as normal with shadow mapping (using depth map) glViewport(0, 0, SCR_WIDTH, SCR_HEIGHT); glClear(GL_COLOR_BUFFER_BIT   GL_DEPTH_BUFFER_BIT); ConfigureShaderAndMatrices(); glBindTexture(GL_TEXTURE_2D, depthMap); RenderScene();</pre>

- First pass: shadow map generation
  - Create a FBO for the shadow map

// configure depth map FBO
const unsigned int SHADOW_WIDTH = 1024, SHADOW_HEIGHT = 1024; shadow map resolution
unsigned int depthMapFBO;
glGenFramebuffers(1, &depthMapFBO);
// create depth texture
unsigned int depthMap;
glGenTextures(1, &depthMap); DL_DEPTH_COMPONENT(16/24/32F)
gibinalexture(Gr_TEXTORE_2D, Geptimap);
glTexImage2D(GL_TEXTURE_2D, 0, GL_DEPTH_COMPONENT, SHADOW_WIDTH, SHADOW_HEIGHT, 0, GL_DEPTH_COMPONENT, GL_FLOAT, NULL);
glTexParameteri(GL_TEXTURE_2D, GL_TEXTURE_MIN_FILTER, GL_NEAREST);
glTexParameteri(GL_TEXTURE_2D, GL_TEXTURE_MAG_FILTER, GL_NEAREST);
glTexParameteri(GL_TEXTURE_2D, GL_TEXTURE_WRAP_S, GL_CLAMP_TO_BORDER);
<pre>glTexParameteri(GL_TEXTURE_2D, GL_TEXTURE_WRAP_T, GL_CLAMP_TO_BORDER);</pre>
<pre>float borderColor[] = { 1.0, 1.0, 1.0, 1.0 };</pre>
glTexParameterfv(GL_TEXTURE_2D, GL_TEXTURE_BORDER_COLOR, borderColor);
// attach depth texture as FBO's depth buffer
glBindFramebuffer(GL_FRAMEBUFFER, depthMapFBO);
glFramebufferTexture2D(GL_FRAMEBUFFER, GL_DEPTH_ATTACHMENT, GL_TEXTURE_2D, depthMap, 0);
g1DrawBuffer(GL_NONE); g1ReadBuffer(GL_NONE); tell OpenGL we don't need a color buffer
glReadBuffer(GL_NONE); ICH OPENGL WE UUTTTHEEU a COIOT DUTTET
glBindFramebuffer(GL_FRAMEBUFFER, 0);

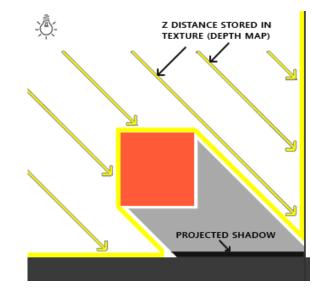
- First pass: shadow map generation
  - Choose a proper resolution





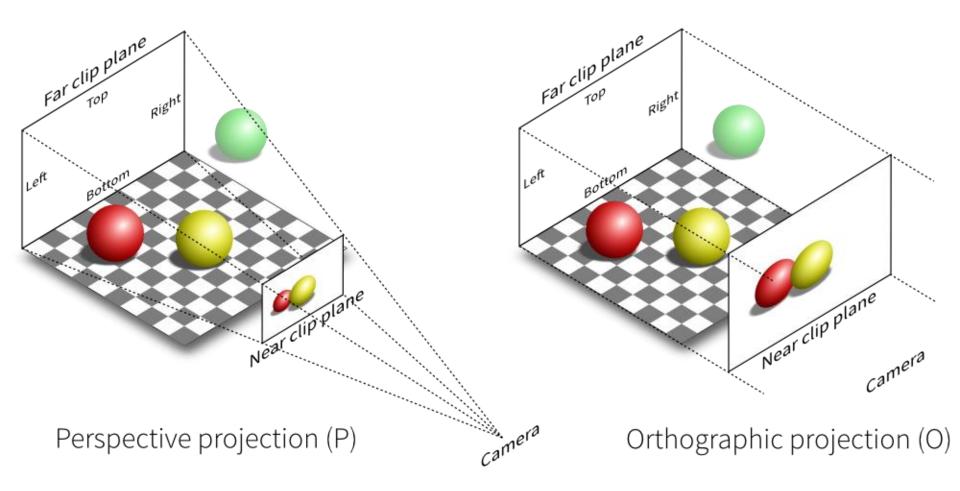


- First pass: shadow map generation
  - A directional light does not have a light position
  - We set the camera to a position somewhere along the lines of the light direction
  - Use orthogonal projection



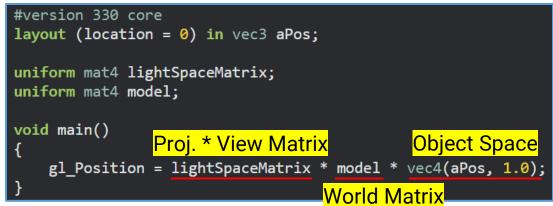
glm::mat4 lightProjection, lightView; glm::mat4 lightSpaceMatrix; float near\_plane = 1.0f, far\_plane = 7.5f; //lightProjection = glm::perspective(glm::radians(45.0f), (GLfloat)SHADOW\_WIDTH / ( lightProjection = glm::ortho(-10.0f, 10.0f, -10.0f, 10.0f, near\_plane, far\_plane); lightView = glm::lookAt(lightPos, glm::vec3(0.0f), glm::vec3(0.0, 1.0, 0.0)); lightSpaceMatrix = lightProjection \* lightView;

### **Recap: Projective Camera Models**

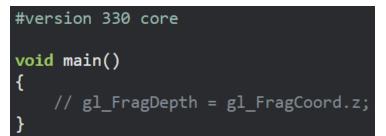


#### First pass: shadow map generation

• Vertex Shader



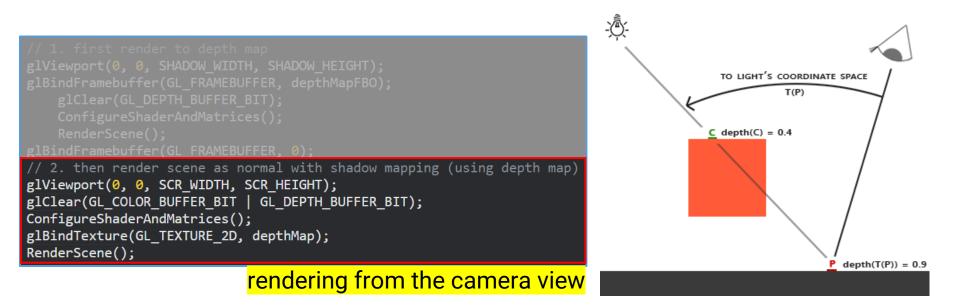
Fragment Shader (do nothing)





#### Second pass: normal rendering

- Render the scene from the camera
- Look up the shadow map to determine shadows during lighting computation



#### Second pass: normal rendering

#### Vertex Shader

```
#version 330 core
layout (location = 0) in vec3 aPos;
layout (location = 1) in vec3 aNormal;
layout (location = 2) in vec2 aTexCoords;
out VS OUT {
   vec3 FragPos;
   vec3 Normal;
   vec2 TexCoords;
   vec4 FragPosLightSpace;
} vs out;
uniform mat4 projection;
uniform mat4 view;
uniform mat4 model;
uniform mat4 lightSpaceMatrix;
                                                                Clip Space coordinate of
void main()
                                                                        light space
                                                                    (for looking up the
   vs out.FragPos = vec3(model * vec4(aPos, 1.0));
   vs out.Normal = transpose(inverse(mat3(model))) * aNormal;
                                                                       shadow map)
   vs out.TexCoords = aTexCoords;
   vs out.FragPosLightSpace = lightSpaceMatrix * vec4(vs out.FragPos, 1.0);
    gl Position = projection * view * vec4(vs out.FragPos, 1.0);
```

#### Second pass: normal rendering

• Fragment Shader

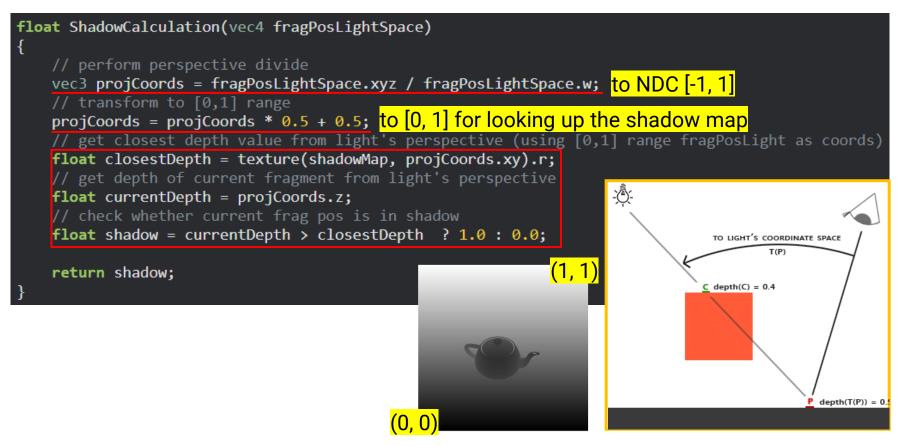
```
#version 330 core
out vec4 FragColor;
in VS_OUT {
    vec3 FragPos;
    vec3 Normal;
    vec2 TexCoords;
    vec4 FragPosLightSpace;
} fs in;
uniform sampler2D diffuseTexture;
uniform sampler2D shadowMap;
uniform vec3 lightPos;
uniform vec3 viewPos;
float ShadowCalculation(vec4 fragPosLightSpace)
    [...]
void main()
    ...
    FragColor = vec4(lighting, 1.0);
```

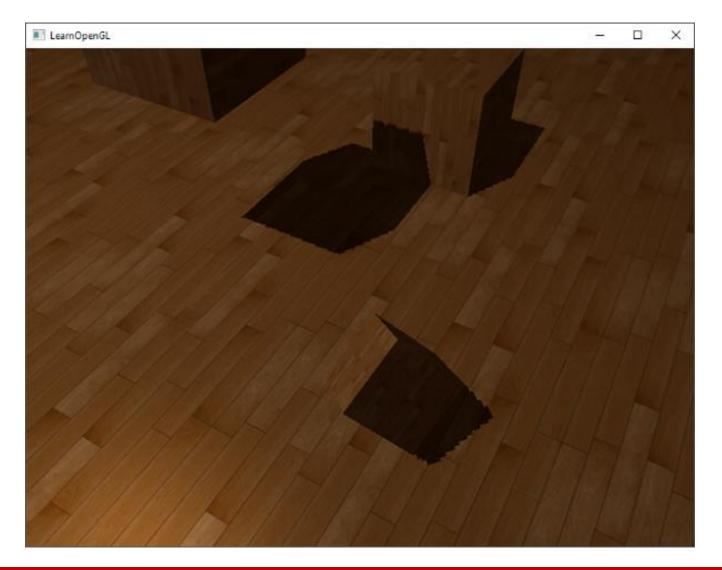
#### Second pass: normal rendering

• Fragment Shader

```
void main()
    vec3 color = texture(diffuseTexture, fs in.TexCoords).rgb;
    vec3 normal = normalize(fs in.Normal);
    vec3 lightColor = vec3(1.0);
    vec3 ambient = 0.15 * lightColor;
    // diffuse
    vec3 lightDir = normalize(lightPos - fs in.FragPos);
    float diff = max(dot(lightDir, normal), 0.0);
    vec3 diffuse = diff * lightColor;
    // specular
    vec3 viewDir = normalize(viewPos - fs in.FragPos);
    float spec = 0.0;
    vec3 halfwayDir = normalize(lightDir + viewDir);
    spec = pow(max(dot(normal, halfwayDir), 0.0), 64.0);
    vec3 specular = spec * lightColor;
   // calculate shadow
   float shadow = ShadowCalculation(fs in.FragPosLightSpace);
   vec3 lighting = (ambient + (1.0 - shadow) * (diffuse + specular)) * color;
    FragColor = vec4(lighting, 1.0);
```

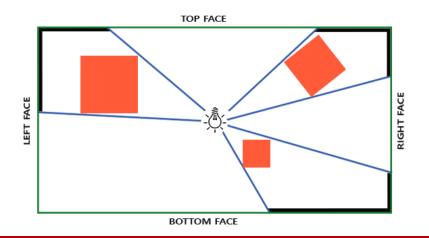
- Second pass: normal rendering
  - Fragment Shader

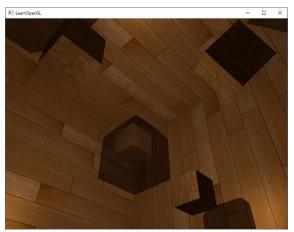




# **Shadow Map for Point / Spot Lights**

- Generate a shadow map for a spotlight is intuitive
  - Locate the camera at the position of the spotlight
  - Use the direction of the spotlight for viewing direction
  - Use **perspective** projection instead of orthogonal projection
- For a point light, you need to render the scene depth into a **cubemap** because the light emits in omni directions
  - <u>https://learnopengl.com/Advanced-Lighting/Shadows/Point-Shadows</u>





## **Percentage Closer Filtering**

- The shadow map has a fixed (and limited) resolution
- A single lookup of a shadow map often produces jagged blocky edges

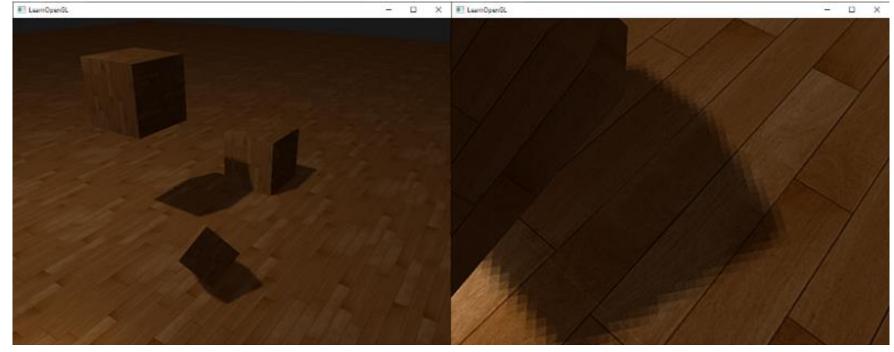


- We can reduce these blocky shadows by increasing the depth map resolution, or
- Sampling more than once from the depth map, each time with slightly different texture coordinates, and averaging the results

### **Percentage Closer Filtering**



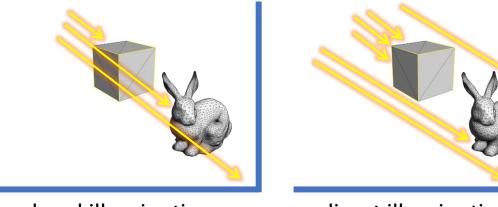
float shadow = 0.0; vec2 texelSize = 1.0 / textureSize(shadowMap, 0); for(int x = -1; x <= 1; ++x) { for(int y = -1; y <= 1; ++y) { float pcfDepth = texture(shadowMap, projCoords.xy + vec2(x, y) \* texelSize).r; shadow += currentDepth - bias > pcfDepth ? 1.0 : 0.0; } } shadow /= 9.0;



### **Ambient Occlusion**

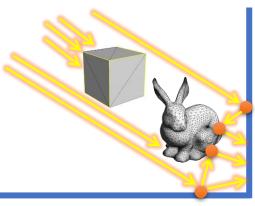
# **Recap: Global Illumination**

- Global illumination includes multi-bounce lighting
- Very expensive to compute
- In Phong lighting model, a constant ambient term is used to account for disregarded illumination
  - However, this produces a "flat", "non-photo-realistic" appearance



local illumination

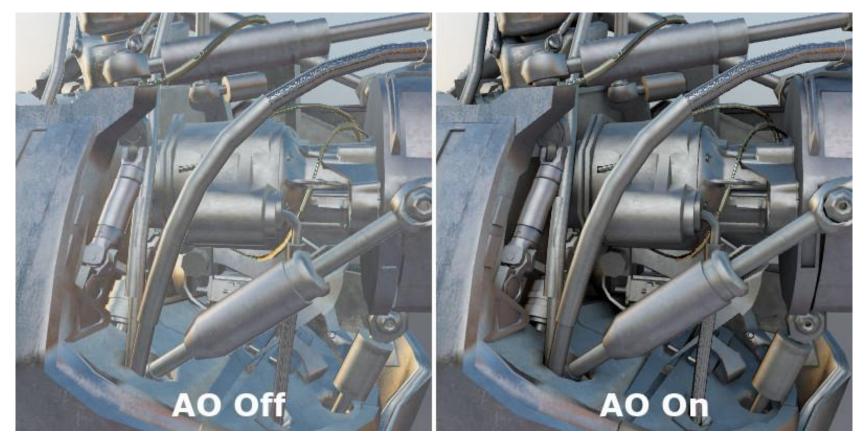
direct illumination



global illumination

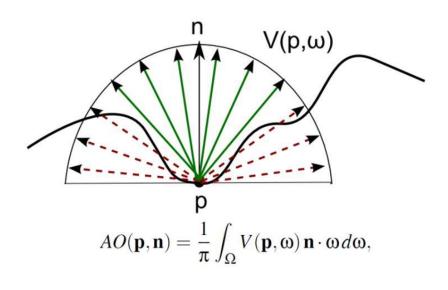
## **Ambient Occlusion**

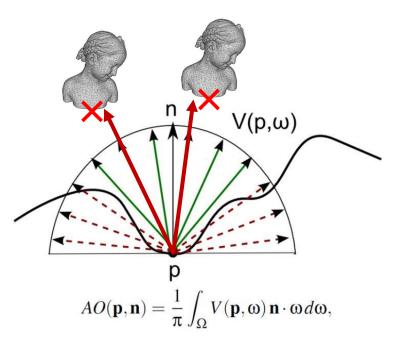
• Ambient occlusion (AO) is a popular technique to approximate global illumination



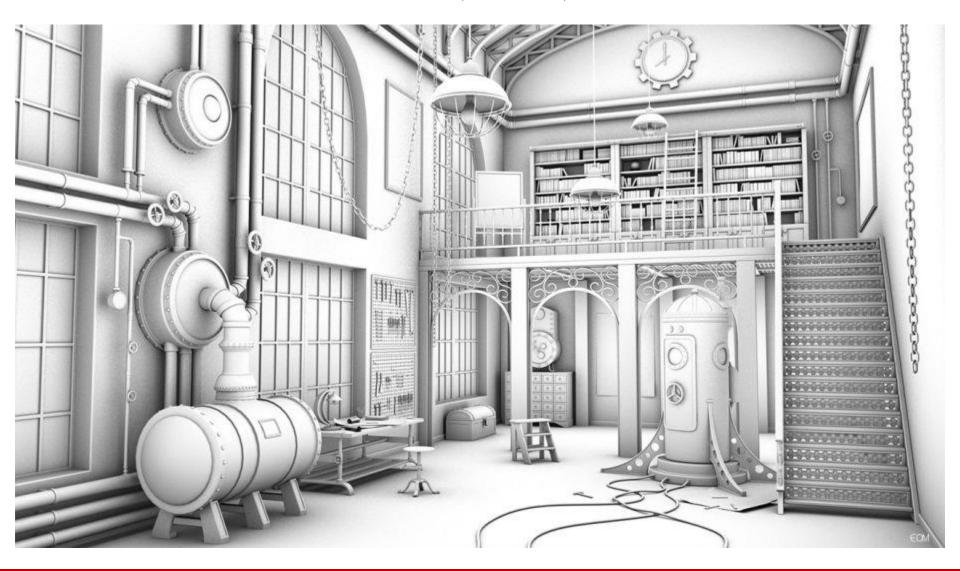
### **Ambient Occlusion (cont.)**

- Ambient occlusion (AO) is a popular technique to approximate global illumination
  - Modulate ambient light by the surface's accessibility
  - Greatly enhance depth perception with a relatively low cost





### **Ambient Occlusion (cont.)**

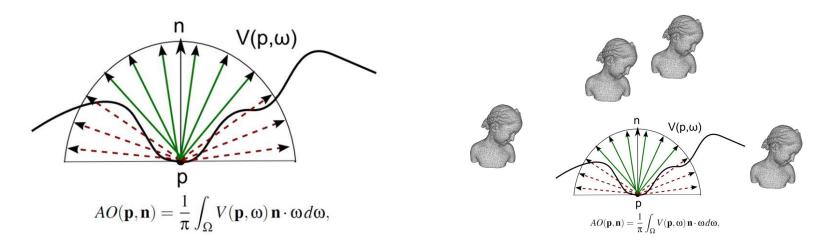


### **Ambient Occlusion (cont.)**

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### **Ambient Occlusion**

- To compute AO, you need to know whether the ambient light is occluded in a direction
- In ray tracing, you can trace rays to determine the visibility
- For rasterization; however, this is difficult because each polygon only knows its information (again!)
  - Performance is also an issue!

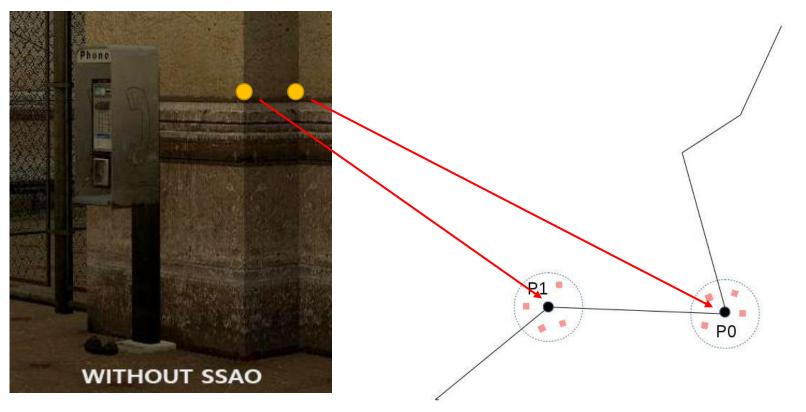


### **Screen-space Ambient Occlusion**

- Crytek implemented a real-time solution for Crysis
  - Quickly became the yardstick for game graphics
  - Known as screen-space ambient occlusion (SSAO)
- Major idea
  - Find nearby occluders in the **depth buffer (screen-space)**

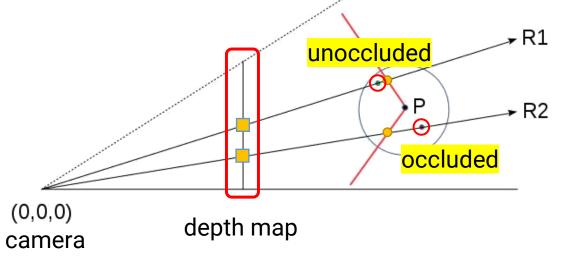


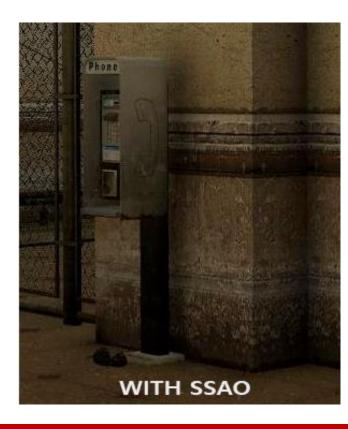
- Method
  - Generate samples within a sphere around the shading point (fragment)



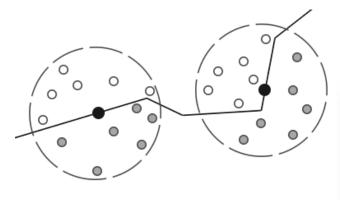
- Method
  - Project the samples back to the depth map from the camera
  - Compare the depth values
  - Average the testing results (AO)
  - Modulate the ambient term with

(1 **–** AO)





- Strike a balance for the sample count (a compromise between quality and performance)
- Use some techniques to trade artifacts (banding) with noise, and later removed them by filtering
  - Obtain acceptable results with few samples





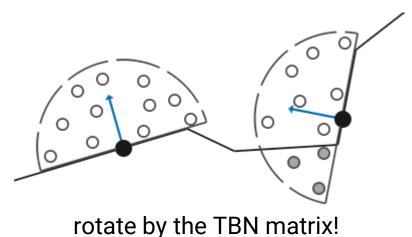
low sample 'banding'



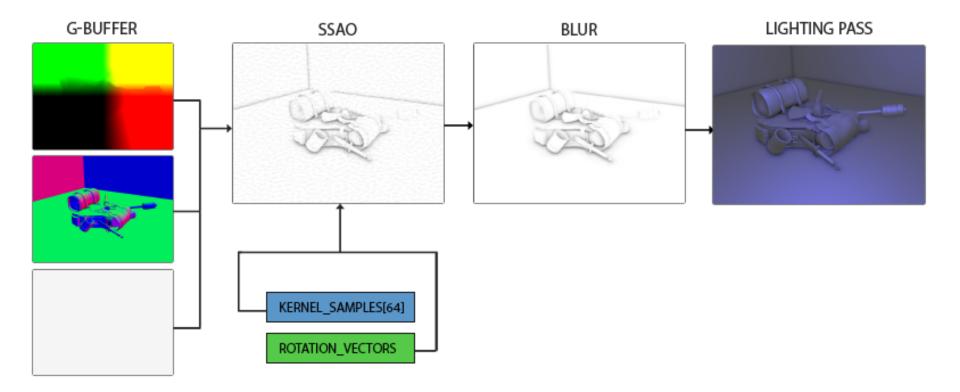
+ blur = acceptable

- Problem and improvement
  - Generate samples within a sphere produces results that are too dark
    - Why? Half of the samples are underneath the surface
  - Solution: use hemisphere (oriented by normal) instead





- An implementation
  - <u>https://learnopengl.com/Advanced-Lighting/SSA0</u>



### **SSAO in Games**



### SSAO in Games (cont.)



