

Ray Tracing

Computer Graphics

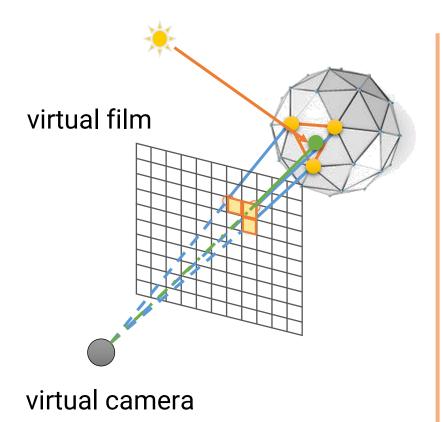
Yu-Ting Wu

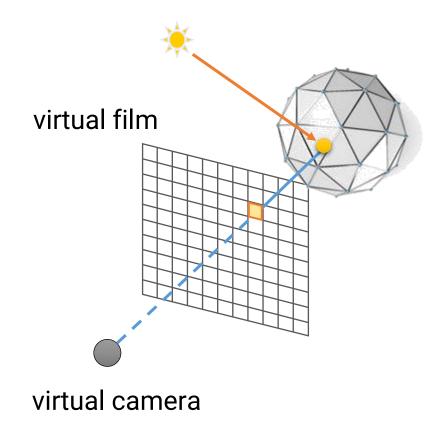
(Some of this slides are borrowed from Prof. Yung-Yu Chuang)

Recap: Digital Image Synthesis

Rasterization

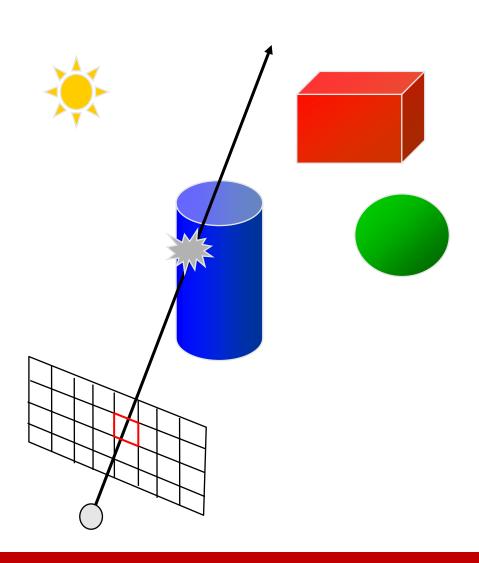
Ray tracing





Ray Casting

• Proposed by Appel [1968]



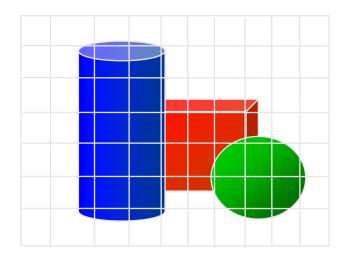
Ray Casting (cont.)

• Proposed by Appel [1968]

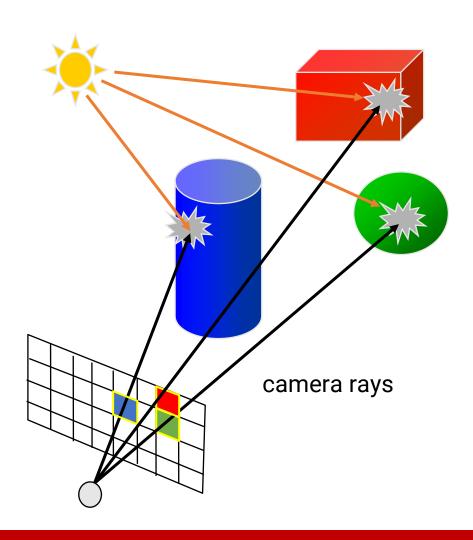
$$K_a I_a + \sum_{i=1}^{nls} I_i \left(K_d \left(L_i \cdot N \right) + K_s \left(R_i \cdot V \right)^n \right)$$

Ray Casting (cont.)

• Proposed by Appel [1968]

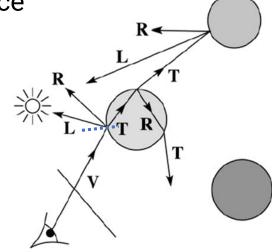


local illumination



Whitted Ray Tracing

- Proposed by Whitted, 1980
- Recursive trace rays for shadows, perfect specular (e.g., mirror), and perfect transparent (e.g., glass) objects
 - For each pixel, trace a primary ray in the direction **V** to the first visible surface
 - For each intersection, trace secondary rays including
 - Shadow rays (L) to each light source
 - Reflected ray (R)
 - Refracted ray (T)



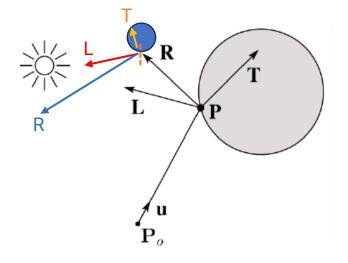
Whitted Ray Tracing (cont.)

- Recursive shading
 - If $I(P_0, u)$ is the intensity seen from the point P along direction u

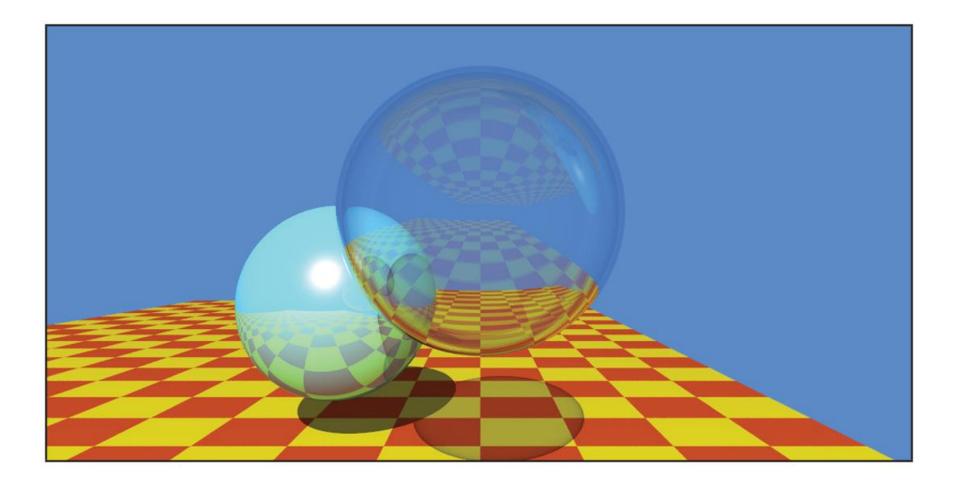
$$I(P_0, u) = I_{\text{direct}} + I_{\text{reflected}} + I_{\text{refracted}}$$

$$I_{\text{direct}} = \text{Shade}(N, L, u, R)$$

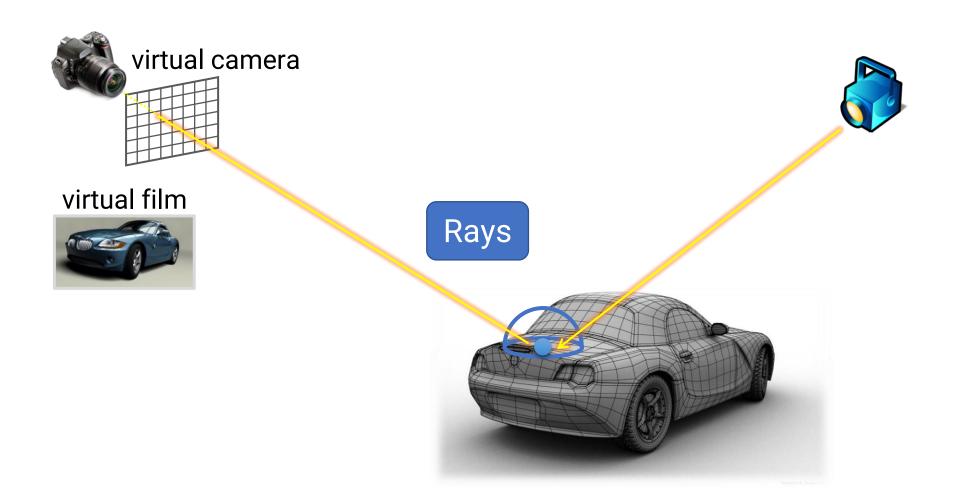
 $I_{\text{reflected}} = I(P, R)$
 $I_{\text{refracted}} = I(P, T)$



Whitted Ray Tracing (cont.)

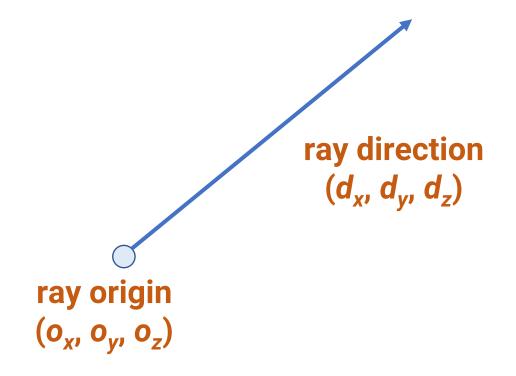


Components of Ray Tracing



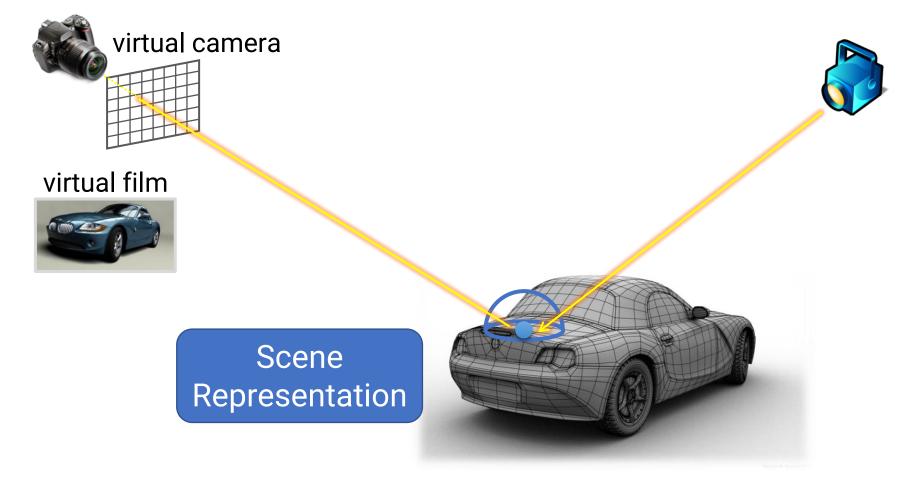
9

Rays



Components of Ray Tracing

• A united approach for different light transport paths

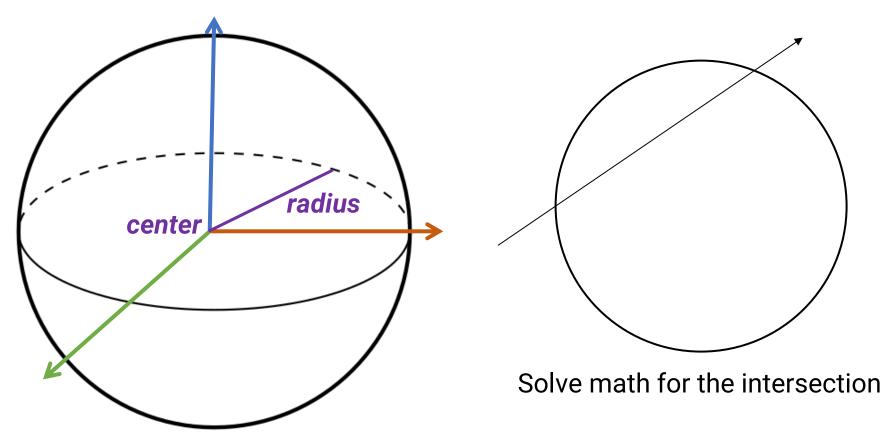


Scene Representation in Ray Tracing

- Basically, just like what you learned in rasterization
 - Also use the idea of object instancing (world transform)
 - Also use camera space (easier to generate rays)
- But **NOT** limited to triangles
- You can use any representation if and only if you can find the intersection of a ray and the surface

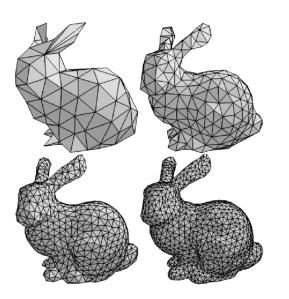
Scene Representation in Ray Tracing (cont.)

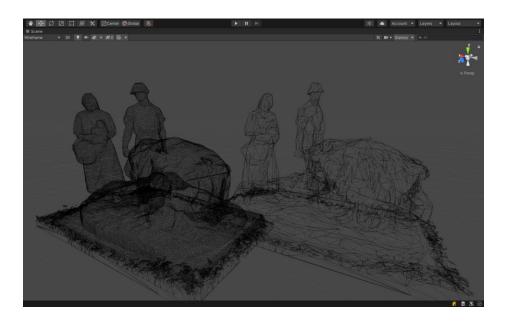
 For example, you can represent a sphere using its center and radius



Scene Representation in Ray Tracing (cont.)

- Triangles are still the most commonly used representation because they can represent arbitrary shapes
- In offline rendering, we usually break up the triangles of objects and treat them "triangle soup"

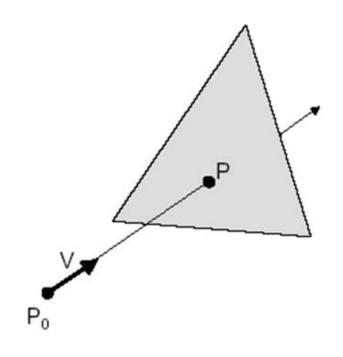


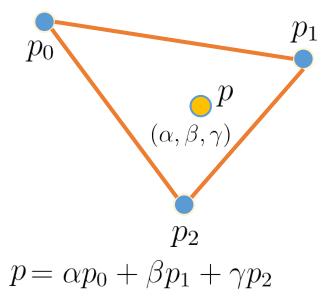


Scene Representation in Ray Tracing (cont.)

Ray-triangle intersection

- Intersect ray with the plane the triangle locates
- Check if the intersection point is inside the triangle
 - Can use barycentric coordinate

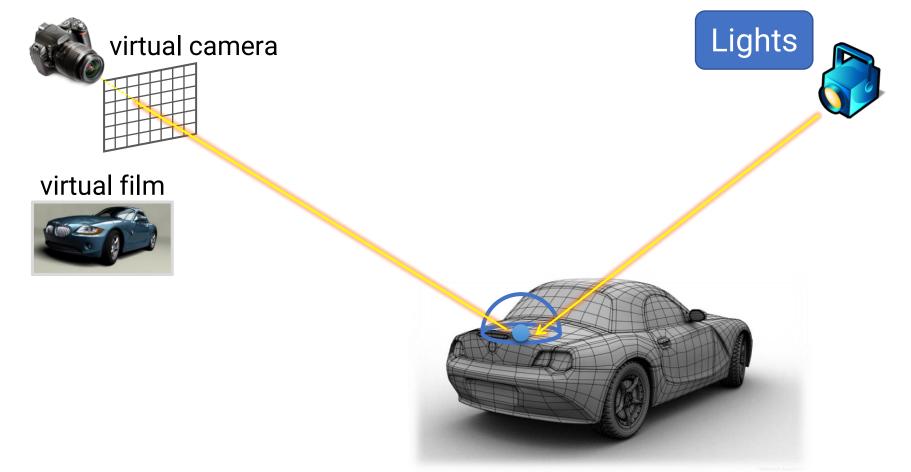




The values α , β , $\gamma \in [0, 1]$ if and only if p is inside the triangle

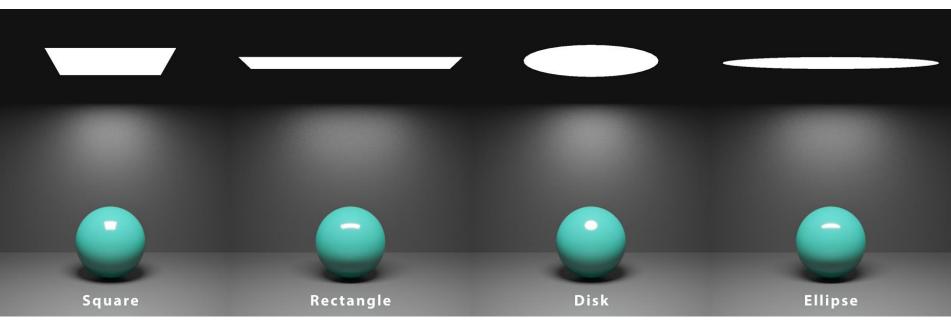
Components of Ray Tracing

• A united approach for different light transport paths



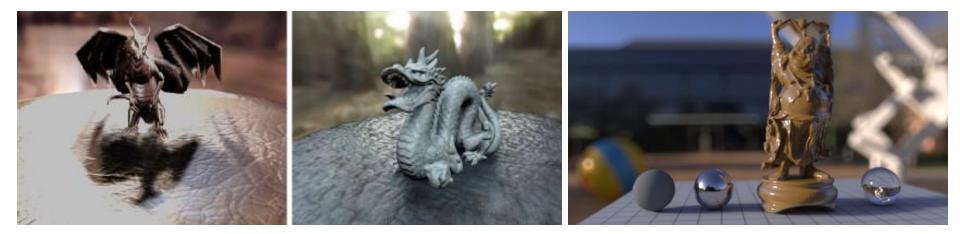
Lights in Ray Tracing

- Basically, just like what you learned in rasterization
- But more complex lights such as area lights and environment lighting are also used for photorealism
 - Estimate the lighting contribution by sampling



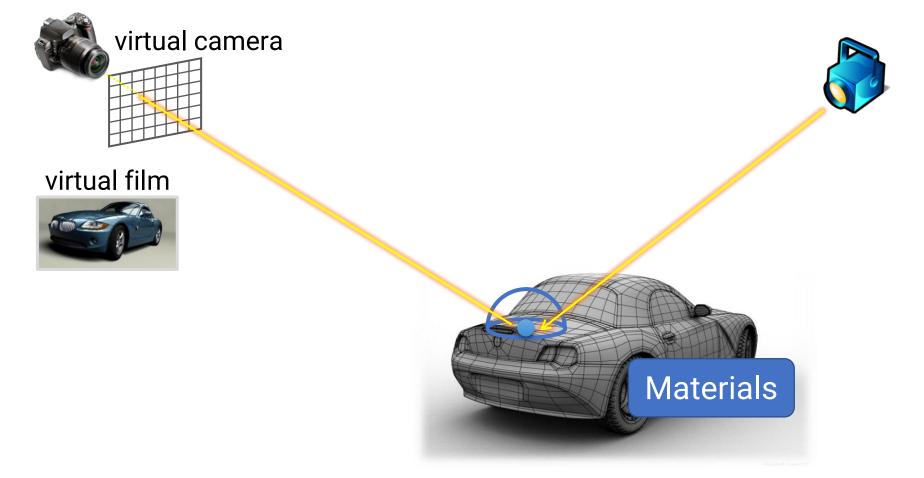
Lights in Ray Tracing

- Basically, just like what you learned in rasterization
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 - Estimate the lighting contribution by **sampling**



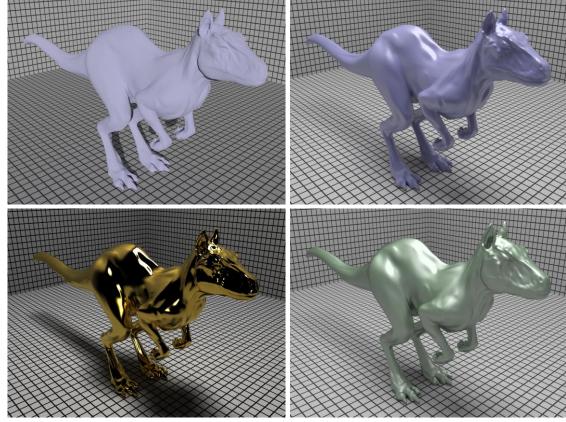
Components of Ray Tracing

• A united approach for different light transport paths



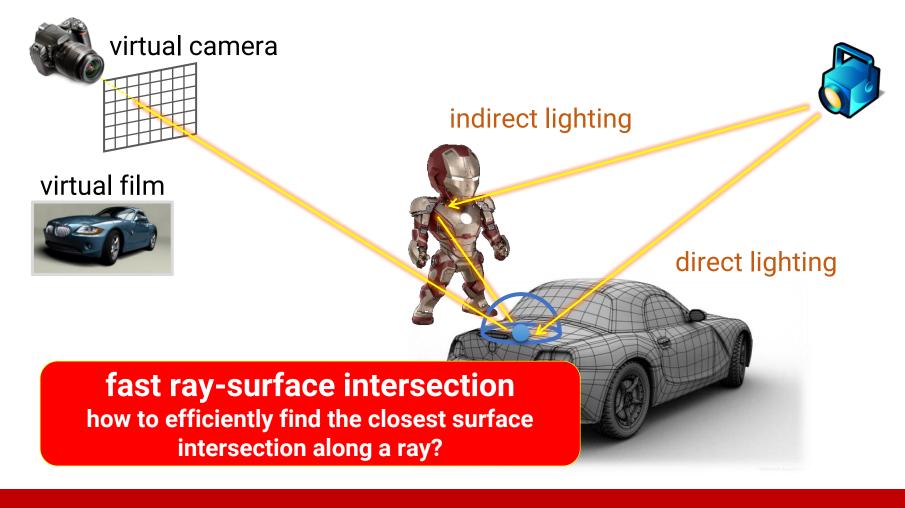
Materials in Ray Tracing

- Basically, just like what you learned in rasterization
- But more complex materials such as the microfacet models



Key: Fast Ray-Surface Intersection

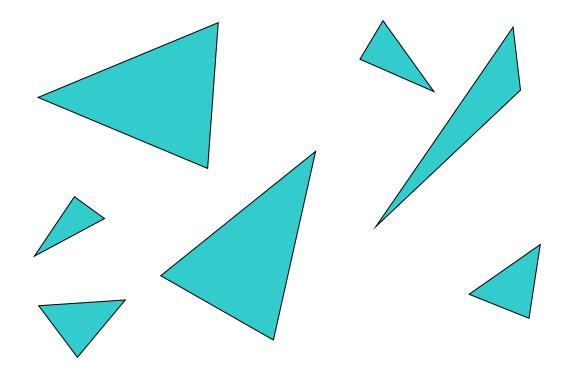
• A united approach for different light transport paths



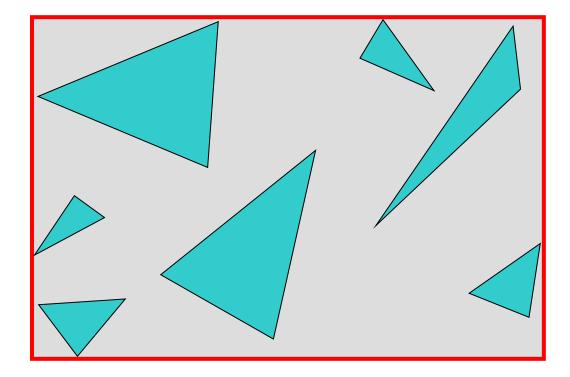
Acceleration Structure

- Reduce the required number of ray-surface intersection
- Common acceleration structures
 - Bounding volume hierarchy (BVH)
 - Space subdivision

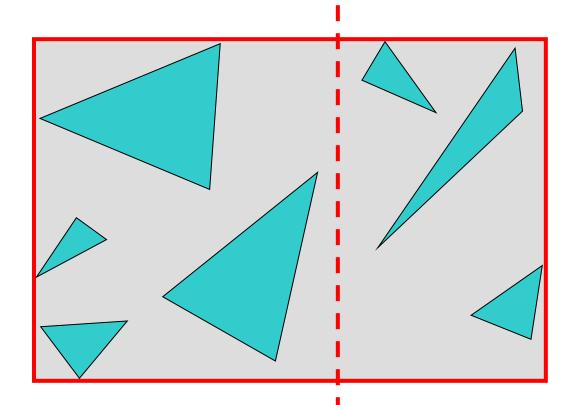
Bounding Volume Hierarchy



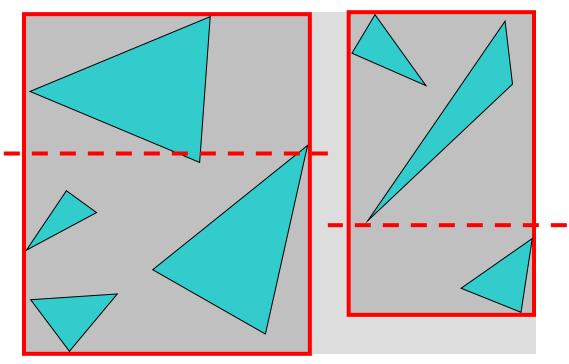
• Find the bounding box of all objects



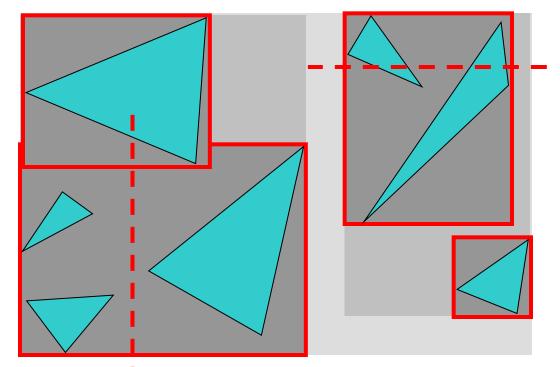
- Find the bounding box of all objects
- Split shapes into two groups



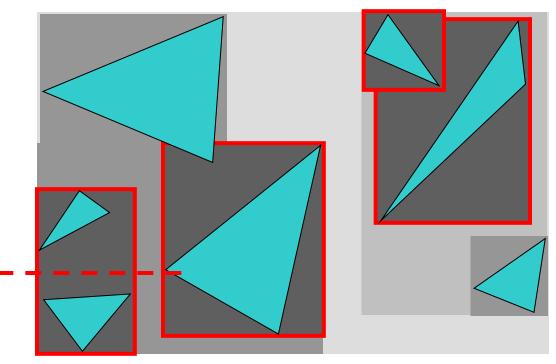
- Find the bounding box of all objects
- Split shapes into two groups
- Recursive



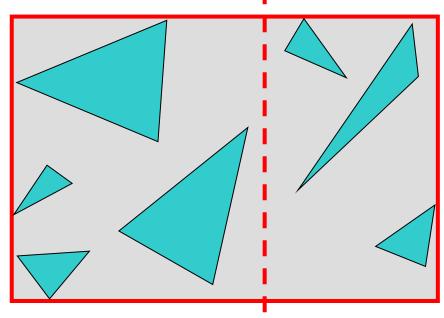
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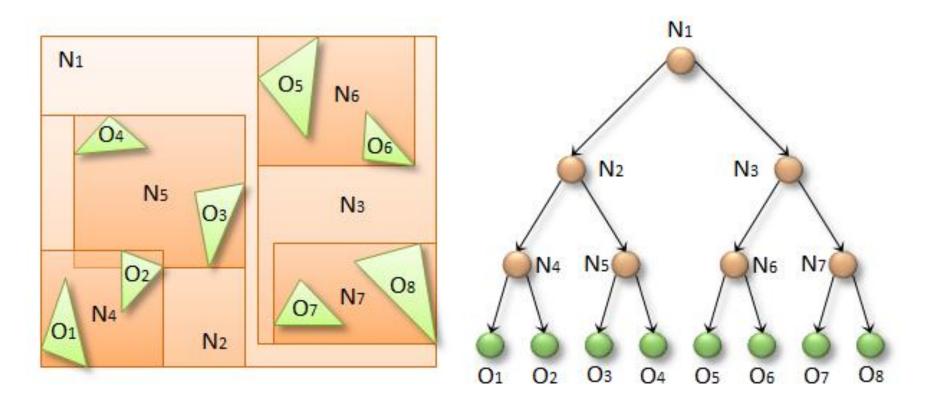
- Find the bounding box of all objects
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- Recursive



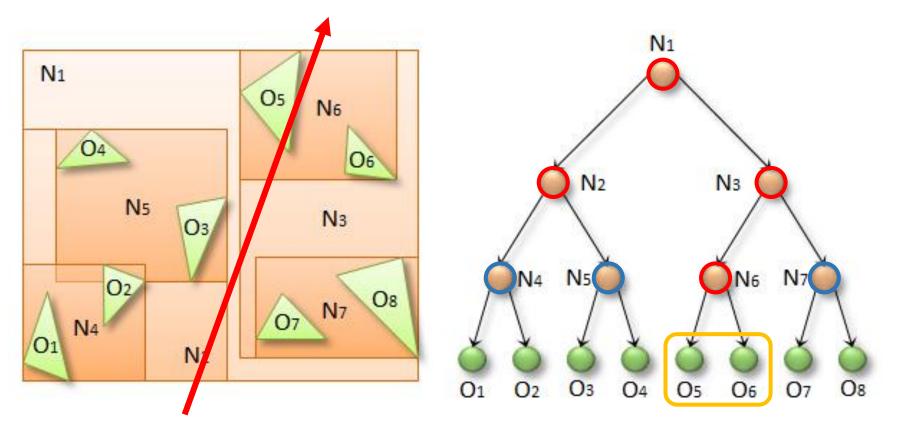
- Where to split?
 - At midpoint
 - Put half of the shapes on each side
 - Use some objective functions, such as surface-area heuristic (SAH)



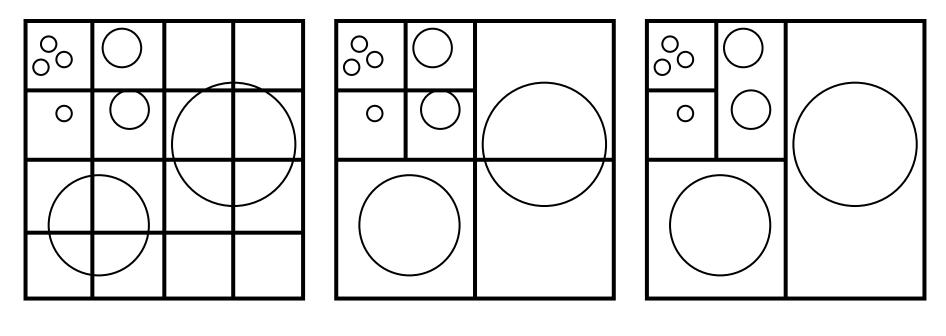
- Preprocess: build a hierarchy of bounding volumes
 - The bounding volume of an interior node contains all children



- **Rendering:** use the hierarchy to accelerate ray intersections
 - Test node contents only if the ray hits the bounding volume



Space Subdivision Approaches

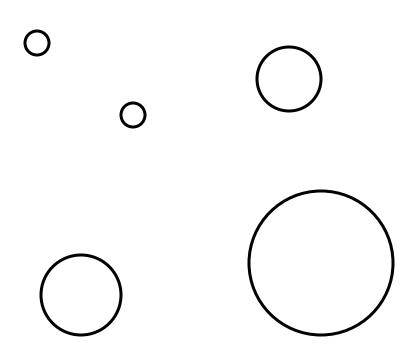


uniform grid

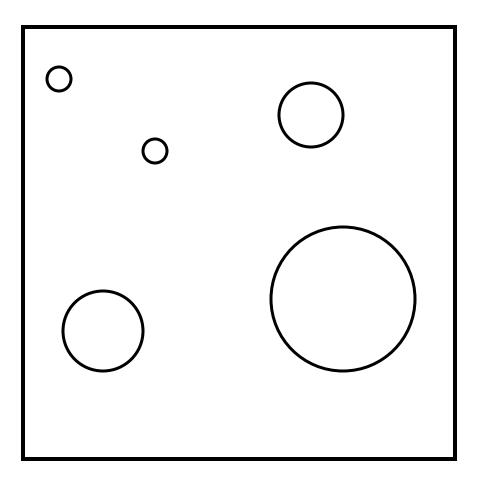
octree

kd tree

Uniform Grid

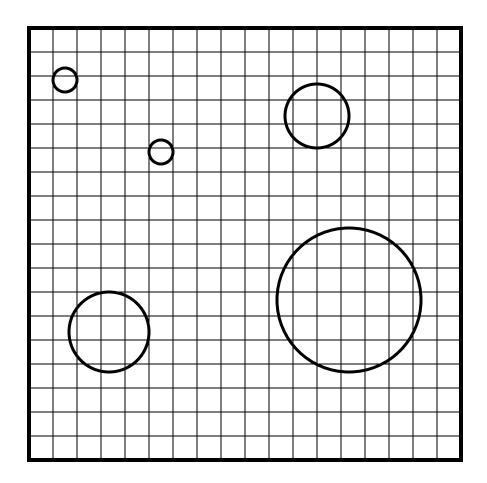


Uniform Grid (cont.)



- Preprocess
 - Find the bounding box

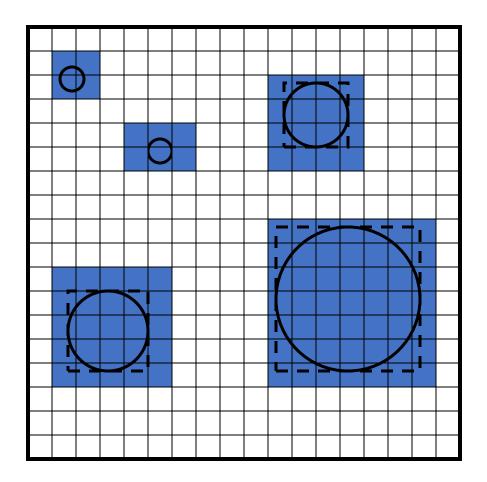
Uniform Grid (cont.)



Preprocess

- Find the bounding box
- Determine grid resolution

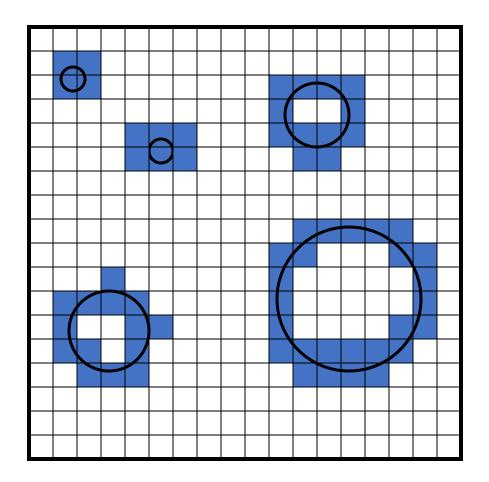
Uniform Grid (cont.)



Preprocess

- Find the bounding box
- Determine grid resolution
- Place a shape in a cell if its bounding box overlaps the cell

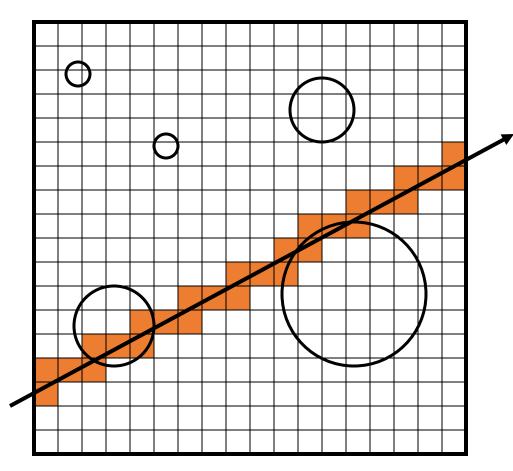
Uniform Grid (cont.)



Preprocess

- Find the bounding box
- Determine grid resolution
- Place a shape in a cell if its bounding box overlaps the cell
- Check that if the shape overlaps the cell

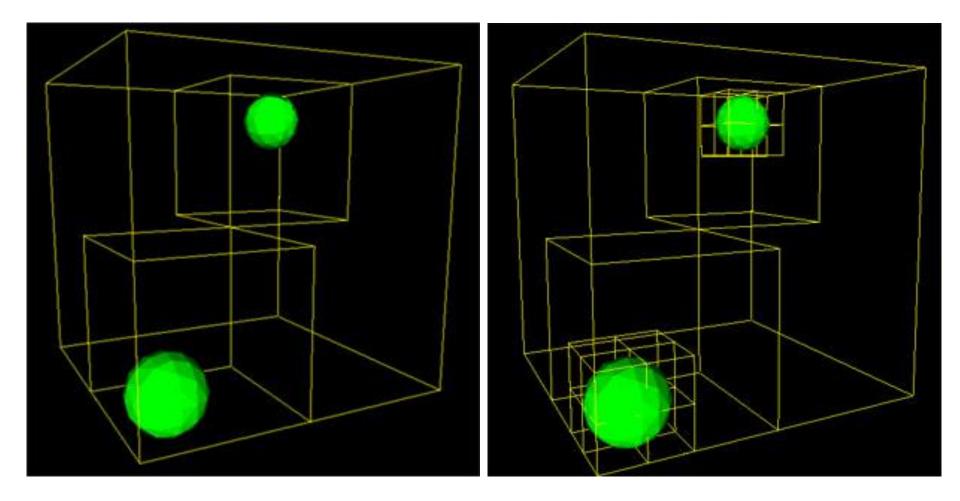
Uniform Grid (cont.)

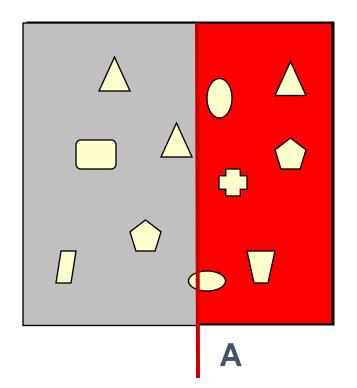


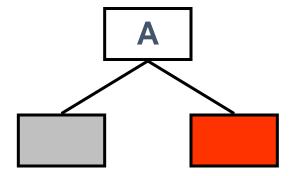
Preprocess

- Find the bounding box
- Determine grid resolution
- Place a shape in a cell if its bounding box overlaps the cell
- Check that if the shape overlaps the cell
- Rendering
 - Use 3D-DDA to traverse the grid

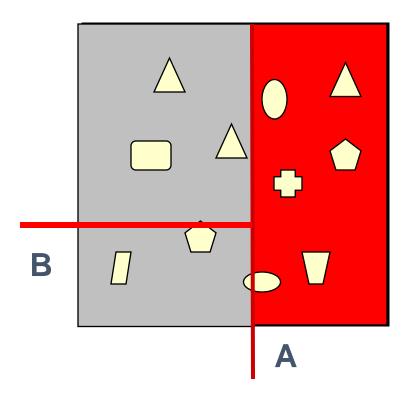
Octree

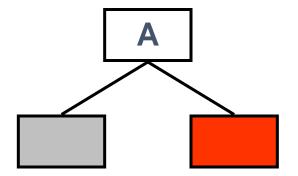


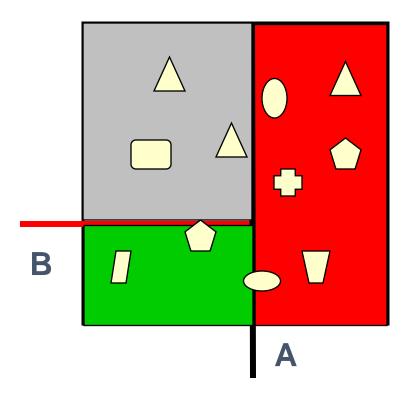


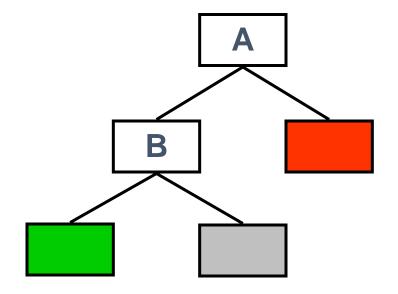


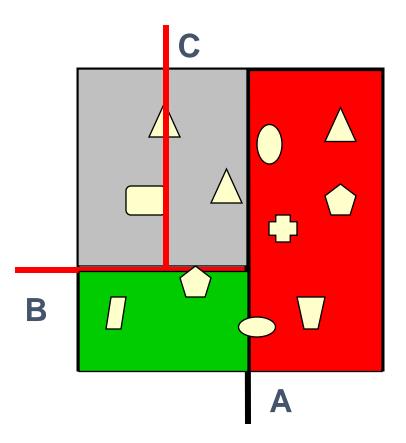
Leaf nodes correspond to unique regions in space

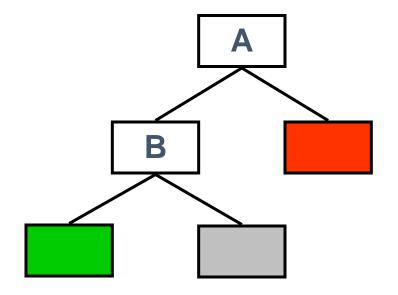


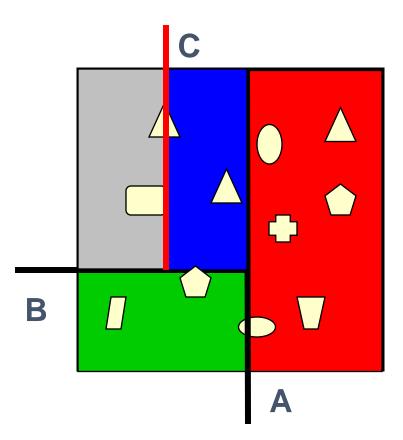


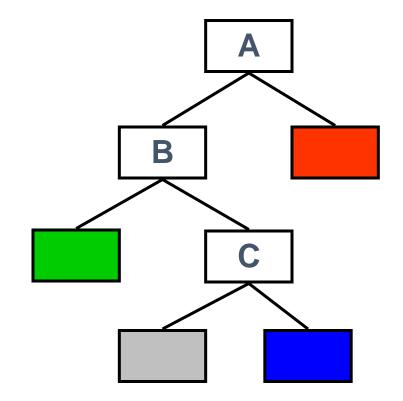


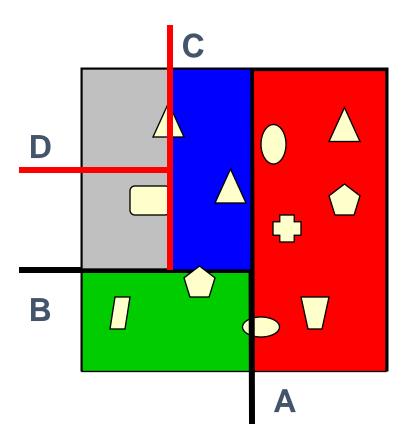


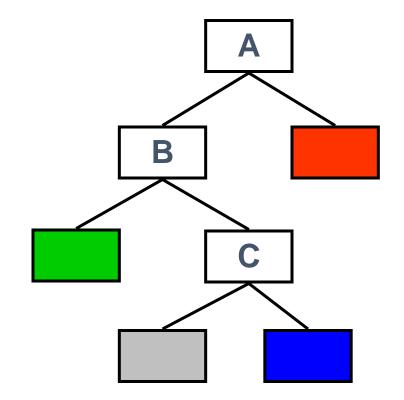


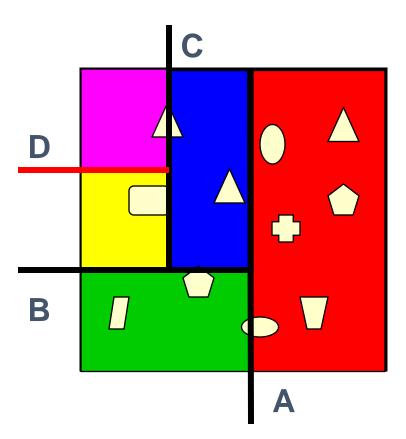


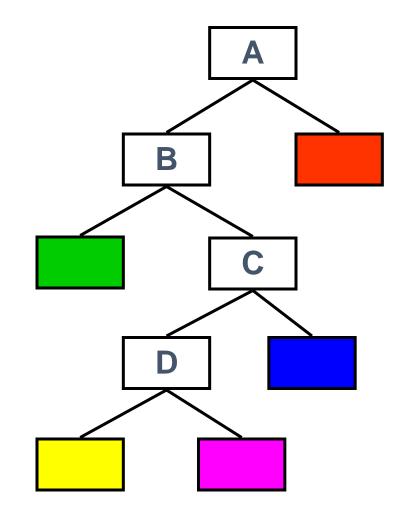


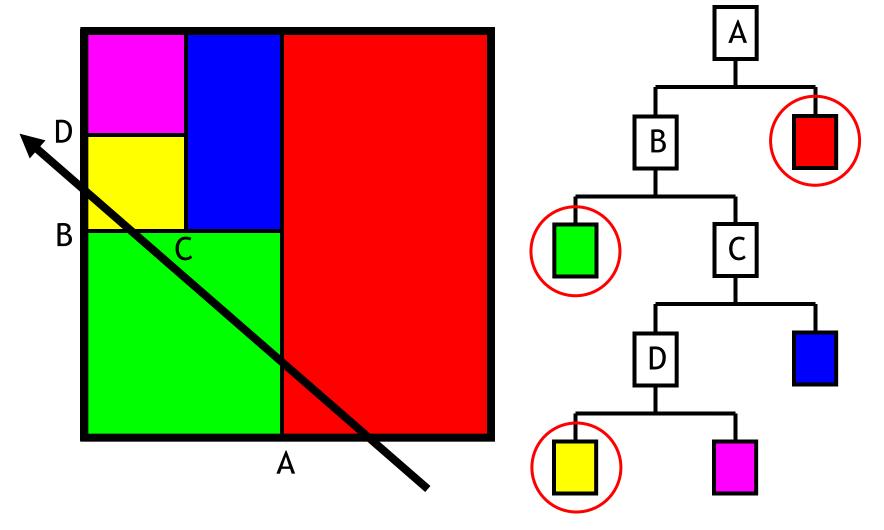




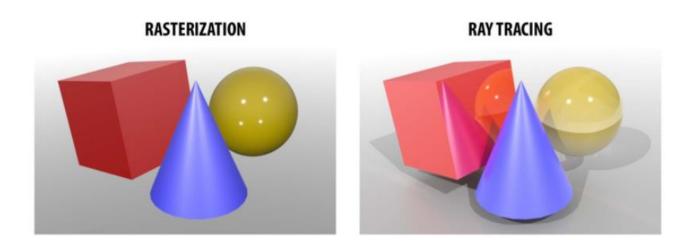








- Rasterization is more friendly to hardware and usually has higher parallelism
- But when we need to **interact with other triangles**, it is much more difficult to simulate effects such as reflection, refraction, shadows, and global illumination
 - Need specialized algorithms



Transparency

- Rasterization
 - Render the object in order (distant objects first) and blend with the previous result in the color buffer
- Ray-tracing:
 - Trace a secondary (refracted) ray through the object's surface

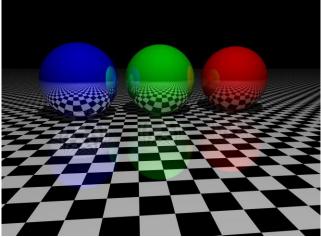




Reflection

- Rasterization
 - Render the scene into an environment map
 - Look up the environment map in the fragment shader
- Ray-tracing:
 - Trace a secondary (reflected) ray from the object's surface

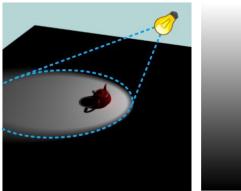




Shadow

Rasterization

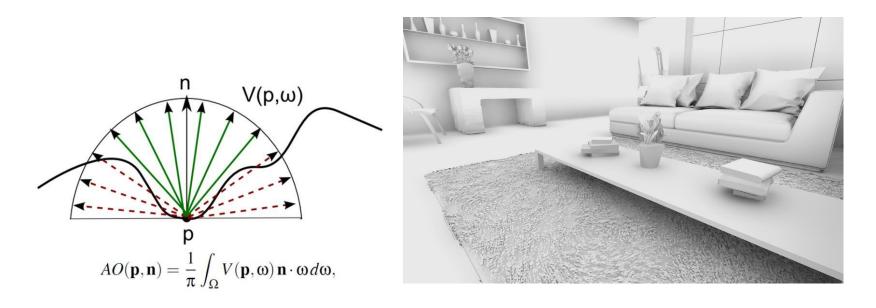
- Render a shadow map to record the closest surface from each light
- Look up the map to determine whether a surface point is in shadow or not in the second pass
- Ray-tracing
 - Trace a shadow ray to see if the lighting direction is occluded



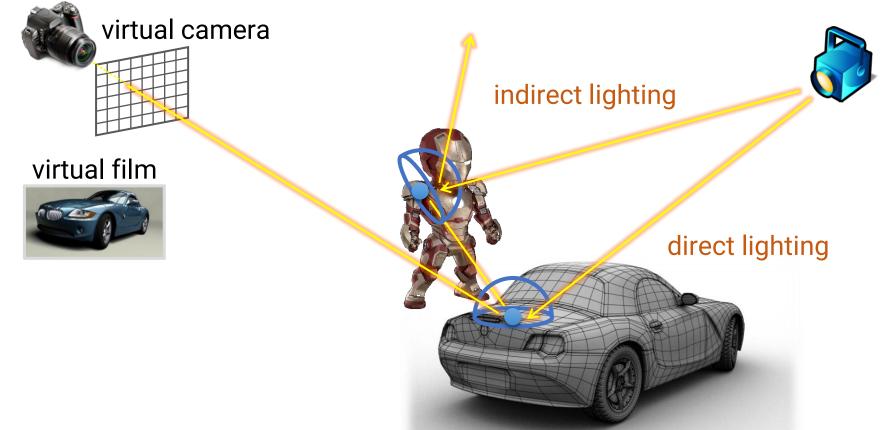




- Ambient occlusion
 - Rasterization
 - Use the **depth map** to find nearby occluders in screen space
 - Ray-tracing
 - Trace shadow rays to see if a direction is occluded



- Global illumination
 - Ray-tracing



Problems with ray tracing

- Ray tracing is more general
- However, its simulator usually has a slow convergence rate and produces lots of noise when samples are not enough
- Solution
 - More rays
 - Filtering



Real-time Ray Tracing

- Recently some GPU ray tracers achieve real-time frame rates by incorporating filtering techniques
 - NVIDIA OptiX
 - <u>https://developer.nvidia.com/rtx/ray-tracing/optix</u>
 - Unreal Engine
 - <u>https://docs.unrealengine.com/5.1/en-US/hardware-ray-tracing-in-unreal-engine/</u>
 - DirectX
 - <u>https://microsoft.github.io/DirectX-Specs/d3d/Raytracing.html</u>
- It is believed to replace rasterization in the future
 - Not that sure now ...

Real-time Ray Tracing

- Unreal Engine Ray Tracing Demo
 - https://www.youtube.com/watch?v=J3ue35ago3Y

