



Bitmapped Images

Multimedia Techniques & Applications

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Outline

- Overview
- Image compression
- Image manipulation
- Geometrical transformations

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Overview

- Record the value of every pixel in the image
- **Image size** is the main cost for the simplicity
- Images created from external devices are usually in a bitmapped fashion
 - Digital cameras
 - Scanners



digital camera



scanner

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Resolution

- A measure of **how finely** a device approximates continuous images using finite pixels
 - Closely related to sampling rates
- Two ways of specifying resolution
 - **Printers and scanners: number of dots per unit**
 - Dots per inch (dpi)
 - Ex: consumer printer (600 dpi), book production (1200 – 2700 dpi), scanners (300 dpi – 3600 dpi)
 - **Video: size of a frame measured in pixels**
 - Ex: 640 x 480, 768 x 576
 - Can translate into the form of dpi if you know the physical dimension of the display device

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Image Compression

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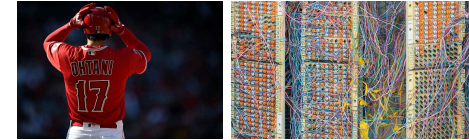
Image Compression

• Motivation

- Faithfully store all pixel values of an image takes lots of memory space
- Human eyes can tolerate some minor errors in images
 - Digital representation is an approximation itself

• Assumption

- Images are usually **smooth** and have some **spatial coherence**

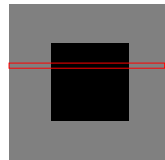


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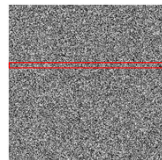
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Compression Methods

- Spend some computation efforts to earn saving in space
- The effectiveness depends on the content of the compressed image
 - **Image size can become bigger after applying compression**
 - Definitely true, otherwise, any data can be compressed into one byte



128 bytes → 6 bytes
for a row (RLE)



128 bytes → 256 bytes
for a row (RLE)

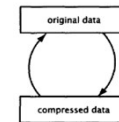
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Compression Methods (cont.)

• Lossless compression

- No information will lose during a compression/decompression cycle
- Ex: run-length encoding (RLE), variable-length coding



• Lossy compression

- Discard some information during the compression process and the information can **never** be recovered
- Ex: JPEG



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Run-Length Encoding (RLE)

- The simplest compression technique
- Each time store a value, followed by a **count** to indicate a number of consecutive pixels of that value
- Example
 - RLE for row1: 128 128
 - 128 bytes (raw) v.s. **2 bytes** (using short)
 - RLE for row2: 128 32 0 64 128 32
 - 128 bytes (raw) v.s. **6 bytes** (using short)

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Huffman Coding

- The best-known variable length coding
- Lossless** compression
- Example:
 - Assume an 8 x 8 image containing 6 different pixel intensities
 - We can count their occurrence:

| | | | | | | |
|------------|----|----|-----|-----|-----|-----|
| intensity | 20 | 60 | 100 | 140 | 180 | 220 |
| occurrence | 5 | 6 | 25 | 16 | 9 | 3 |

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Huffman Coding (cont.)

- Algorithm**
 - Build a Huffman tree
 - Sort the occurrence of intensity

| | | | | | |
|----|----|-----|-----|-----|-----|
| 20 | 60 | 100 | 140 | 180 | 220 |
| 5 | 6 | 25 | 16 | 9 | 3 |

- Merge the two with the smallest occurrence, and sort again

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Huffman Coding (cont.)

- Algorithm**
 - Build a Huffman tree
 - Keep doing ...

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Huffman Coding (cont.)

- Algorithm
 - Build a Huffman tree
 - Keep doing ...

| | | | | | |
|----|----|-----|-----|-----|-----|
| 20 | 60 | 100 | 140 | 180 | 220 |
| 5 | 6 | 25 | 16 | 9 | 3 |

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Huffman Coding (cont.)

- Algorithm
 - Build a Huffman tree
 - Keep doing ...

| | | | | | |
|----|----|-----|-----|-----|-----|
| 20 | 60 | 100 | 140 | 180 | 220 |
| 5 | 6 | 25 | 16 | 9 | 3 |

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Huffman Coding (cont.)

- Algorithm
 - Build a Huffman tree
 - Keep doing ...

Once we have done, the leaf nodes are the initial data items

| | | | | | |
|----|----|-----|-----|-----|-----|
| 20 | 60 | 100 | 140 | 180 | 220 |
| 5 | 6 | 25 | 16 | 9 | 3 |

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Huffman Coding (cont.)

- Algorithm
 - Build a Huffman tree
 - Label the code (from root)

| | | | | | |
|----|----|-----|-----|-----|-----|
| 20 | 60 | 100 | 140 | 180 | 220 |
| 5 | 6 | 25 | 16 | 9 | 3 |

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Huffman Coding (cont.)

- **Algorithm**
 - Build a Huffman tree
 - Label the code (from root)
 - We will obtain
 - 100: 0
 - 140: 10
 - 180: 110
 - 60: 1110
 - 220: 11110
 - 20: 11111

Average number of bit per data:
 $1*(25/64)+2*(16/64)+3*(9/64)+4*(6/64)+5*(3/64)+5*(5/64)$
 $= 2.31$ (compared to raw, 8 bit, and naïve encoding, 3 bit)

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JPEG Compression

- JPEG is the most important **lossy** compression technique, which stands for **Joint Photographic Experts Group**
 - Related file formats: *.jpg / *.jpeg / *.jpe / *.jfif / *.jfi / *.jif
- It works because image data can tolerate a certain amount of data loss

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JPEG Compression (cont.)

- **RGB → YCbCr**
 - People are more sensitive to intensity (Y) and less sensitive to color (Cb, Cr)
 - Cb and Cr are lower frequency and have more spatial coherence
 - Compress Cb and Cr; while keep Y as it is

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JPEG Compression (cont.)

- **Divide into 8x8 blocks (for Cb & Cr)**
 - The entire image is too difficult to compress
 - Small image block has higher coherence

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JPEG Compression (cont.)

```

    graph LR
      A[RGB → YCbCr] --> B[divide into 8x8 blocks]
      B --> C[DCT]
      C --> D[Quantization]
      D --> E[zigzag ordering]
      E --> F[RLE / Huffman]
  
```

- **Discrete Cosine Transform (DCT)**
 - A method for transforming a waveform into its frequency domain
 - The DCT of an image block is the coefficients of different cosines of the image block

image DFT result DCT result

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JPEG Compression (cont.)

```

    graph LR
      A[RGB → YCbCr] --> B[divide into 8x8 blocks]
      B --> C[DCT]
      C --> D[Quantization]
      D --> E[zigzag ordering]
      E --> F[RLE / Huffman]
  
```

- **Quantization**
 - Human are less sensitive to high-frequency signal
 - Use fewer bits for high-frequency signals in the DCT result and vice versa
 - **This step is the reason of lossy compression**
 - After this step, many components will end up with zero coefficients

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JPEG Compression (cont.)

```

    graph LR
      A[RGB → YCbCr] --> B[divide into 8x8 blocks]
      B --> C[DCT]
      C --> D[Quantization]
      D --> E[zigzag ordering]
      E --> F[RLE / Huffman]
  
```

- **Zigzag ordering**
 - For later Huffman encoding
 - Result in a longer zero sequence

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JPEG Compression (cont.)

```

    graph LR
      A[RGB → YCbCr] --> B[divide into 8x8 blocks]
      B --> C[DCT]
      C --> D[Quantization]
      D --> E[zigzag ordering]
      E --> F[RLE / Huffman]
  
```

- **RLE / Huffman encoding**
 - Different strategy for DC and AC term
 - The DC components of different blocks are encoded using Huffman algorithm
 - The AC components within a block are encoded using RLE

DC AC

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JPEG Compression (cont.)

- The decompression of JPEG data is done by reversing the compression process
- We can control the degree of compression by altering the amount of quantization
- JPEG compression usually achieves very high compression rate for natural images (5% of the original size)

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Image Manipulation

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Image Manipulation

- **Motivations**
 - Correct deficiencies in an image (e.g., noise, red-eye)
 - Create images that are difficult or impossible to make naturally (e.g., glow)
- Type of image manipulations
 - Pixel **point** processing
 - Pixel **group** processing

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Pixel Point Processing

- Compute a pixel's new value solely on the basis of its old value

mapping function

$$p' = f(p)$$

- Some examples
 - Adjustment of brightness
 - Adjustment of contrast
 - Change the black and white levels



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Color Curve

- The operations can be considered generally as altering the mapping function f
- Color curve**

new pixel value

original pixel value

$p' = p$

255

180

160

128

64

96

128

170

255

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Histogram

- An approximate representation of the **distribution** of numerical data

Intensity Image

Number of pixels

Intensity

2000

1800

1600

1400

1200

1000

800

600

400

200

0

0

50

100

150

200

250

300

Histogram

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Pixel Group Processing

- Compute each pixel's new value as a function not just of its old value, but also of **the values of neighboring pixels**
- Usually related to **filtering**
 - For a pixel of an image, specify a two-dimensional array of weights of its neighbors
 - Several types of filters
 - Smoothing
 - Sharpening
 - Detecting edge

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Box Filter

- Each neighbor has the same weight

original image

box filter

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Box Filter (cont.)

convolution mask
convolution kernel

filter

| | | |
|-----|-----|-----|
| 1/9 | 1/9 | 1/9 |
| 1/9 | 1/9 | 1/9 |
| 1/9 | 1/9 | 1/9 |

image (signal)

| | | | |
|---|---|---|---|
| 0 | 0 | 9 | 9 |
| 0 | 0 | 9 | 9 |
| 0 | 0 | 9 | 9 |
| 0 | 0 | 9 | 9 |

filtered image (signal)

| | | | |
|---|---|---|---|
| 0 | 3 | 6 | 9 |
| 0 | 3 | 6 | 9 |
| 0 | 3 | 6 | 9 |
| 0 | 3 | 6 | 9 |

$(1/9*0+1/9*0+1/9*0+1/9*0+1/9*0+1/9*0+1/9*0+1/9*9+1/9*9+1/9*9)$

Input f(x,y) * Convolution operator, not multiplication! = Output g(x,y)

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Box Filter (cont.)

- 1D visualization of kernel weight

box filter

gaussian filter

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Gaussian Filter

- The weight of neighbor falls exponentially with its distance to the filtered pixel
 - Standard deviation σ controls the speed of decreasing

$$g(x, y) = \frac{1}{2\pi\sigma^2} e^{-\frac{x^2+y^2}{2\sigma^2}}$$

distance: x^2+y^2
 standard deviation: $2\sigma^2$
 normalization (sum of weight = 1)

| | | | | |
|---|----|----|----|---|
| 1 | 4 | 7 | 4 | 1 |
| 4 | 16 | 26 | 16 | 4 |
| 7 | 26 | 41 | 26 | 7 |
| 4 | 16 | 26 | 16 | 4 |
| 1 | 4 | 7 | 4 | 1 |

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Gaussian Filter (cont.)

input

per-pixel multiplication

output

average

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Box Filter v.s. Gaussian Filter

original image box filter gaussian filter

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Bilateral Filter

- Properties of Gaussian filter

$$g(x, y) = \frac{1}{2\pi\sigma^2} e^{-\frac{x^2+y^2}{2\sigma^2}}$$

range of the filter

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Bilateral Filter (cont.)

- Problems of Gaussian filter
 - Does smooth images
 - But smooths too much: **edges are blurred**
 - Only spatial distance matters
 - No edge term

$$GB[I]_p = \sum_{q \in S} G_\sigma(\|\mathbf{p} - \mathbf{q}\|) I_q$$

spatial distance

$$g(x, y) = \frac{1}{2\pi\sigma^2} e^{-\frac{x^2+y^2}{2\sigma^2}}$$

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Bilateral Filter (cont.)

- Problems of Gaussian filter
 - Same Gaussian kernel everywhere

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Bilateral Filter (cont.)

- Combine another Gaussian weight computed by **intensity difference (edge preserving)**

$$GB[I]_p = \sum_{q \in S} G_{\sigma_s}(\|p - q\|) I_q$$

↓

$$BF[I]_p = \frac{1}{W_p} \sum_{q \in S} G_{\sigma_s}(\|p - q\|) G_{\sigma_r}(I_p - I_q) I_q$$

spatial distance range (intensity) distance
NEW!

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Bilateral Filter (cont.)

- Visualization

$$BF[I]_p = \frac{1}{W_p} \sum_{q \in S} G_{\sigma_s}(\|p - q\|) G_{\sigma_r}(I_p - I_q) I_q$$

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Bilateral Filter (cont.)

- Parameters

$$BF[I]_p = \frac{1}{W_p} \sum_{q \in S} G_{\sigma_s}(\|p - q\|) G_{\sigma_r}(I_p - I_q) I_q$$

- Spatial sigma σ_s** : spatial extent of the kernel, size of the considered neighborhood
- Range sigma σ_r** : "minimum" amplitude of an edge

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Bilateral Filter (cont.)

- Parameters

| | $\sigma_r = 0.1$ | $\sigma_r = 0.25$ | $\sigma_r = \infty$ (Gaussian blur) |
|-----------------|------------------|-------------------|--|
| $\sigma_s = 2$ | | | |
| $\sigma_s = 6$ | | | |
| $\sigma_s = 18$ | | | |


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Bilateral Filter Application (cont.)

- Denoising




noisy input Median Filter 5x5

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Bilateral Filter Application (cont.)

- Denoising




noisy input Bilateral Filter 7x7

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Bilateral Filter Application (cont.)

- Denoising



noisy input Gaussian Filter Bilateral Filter

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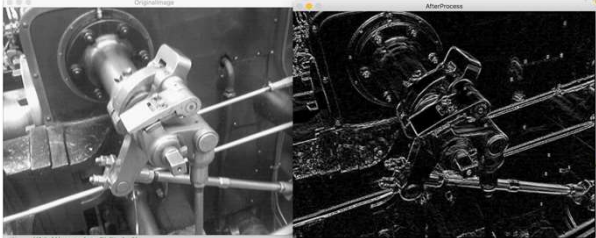
Sobel Filter

- Negative weights are commonly used for edge detection

| | | |
|----|---|----|
| -1 | 0 | +1 |
| -2 | 0 | +2 |
| -1 | 0 | +1 |

| | | |
|----|----|----|
| +1 | +2 | +1 |
| 0 | 0 | 0 |
| -1 | -2 | -1 |

Gx Gy



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Photographic Style Transfer

- Two-scale Tone Management for Photographic Look, Bae et al. SIGGRAPH 2006

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Photographic Style Transfer (cont.)

- Motivation

Ansel Adams
Clearing Winter Storm

An Amateur Photographer

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Photographic Style Transfer (cont.)

- Motivation

Ansel Adams
Clearing Winter Storm

style transferred result
(an imitation of Ansel Adams)

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Photographic Style Transfer (cont.)

- Observation
 - Different photographers have different tonal styles
 - Global contrast

high global contrast

low global contrast

Ansel Adams

Kenro Izu

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Photographic Style Transfer (cont.)

- **Observation**
 - Different photographers have different tonal styles
 - Global contrast
 - Local contrast

Ansel Adams Kenro Izu

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Photographic Style Transfer (cont.)

- **Goal**
 - Transfer look between photographers

input image model result

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Photographic Style Transfer (cont.)

- **Algorithm**

input image split global contrast local contrast combine result

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Photographic Style Transfer (cont.)

- **Algorithm**
 - Separate global and local contrast
 - Gaussian filter produces blurring and halos

input image smooth low frequency (global contrast) diff high frequency (local contrast)

blur halo

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Photographic Style Transfer (cont.)

- **Algorithm**
 - Separate global and local contrast
 - Bilateral filter can do a better job

input image

smooth

base layer
low frequency
(global contrast)

diff

input image

detail layer
high frequency
(local contrast)

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Photographic Style Transfer (cont.)

- **Algorithm**
 - Separate global and local contrast

input image

split

global contrast

local contrast

combine

result

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Photographic Style Transfer (cont.)

- **Algorithm**
 - Adjust global contrast by histogram matching

input image

split

global contrast

local contrast

combine

result

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Photographic Style Transfer (cont.)

- **Algorithm**
 - Adjust local contrast by uniformly scaling

input image

split

global contrast

local contrast

detail x 3

combine

result

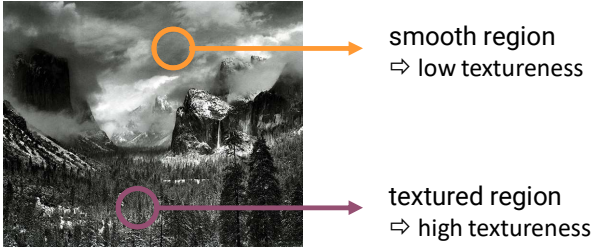
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Photographic Style Transfer (cont.)

- **Algorithm**
 - Sometimes the local contrast is not uniform



smooth region
=> low texture

textured region
=> high texture

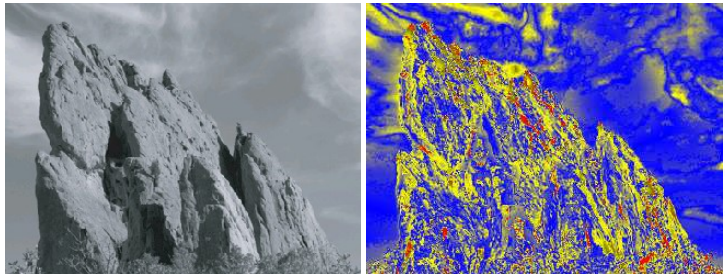
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Photographic Style Transfer (cont.)

- **Algorithm**
 - Textureness computation



input textureness

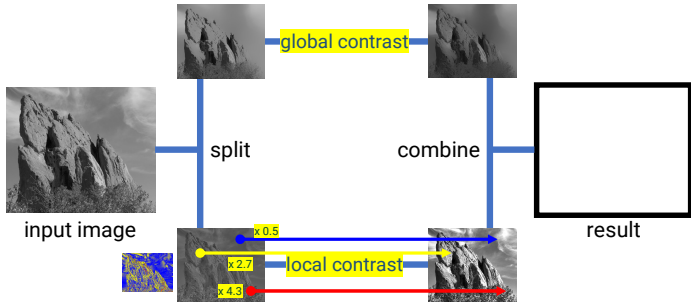
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Photographic Style Transfer (cont.)

- **Algorithm**
 - Non-uniformly increase local contrast based on textureness



input image

split

global contrast

combine

result

local contrast

x0.5

x2.7

x4.3

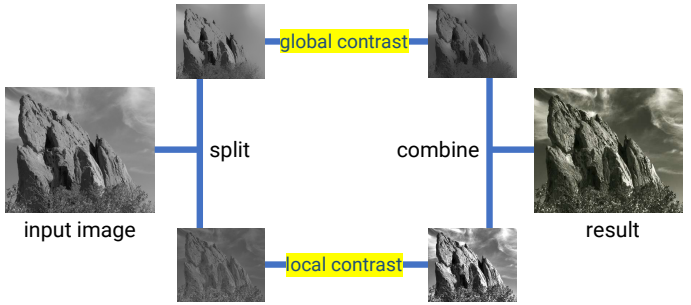
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Photographic Style Transfer (cont.)

- **Algorithm**
 - Combine global and local contrast



input image

split

global contrast

combine

result

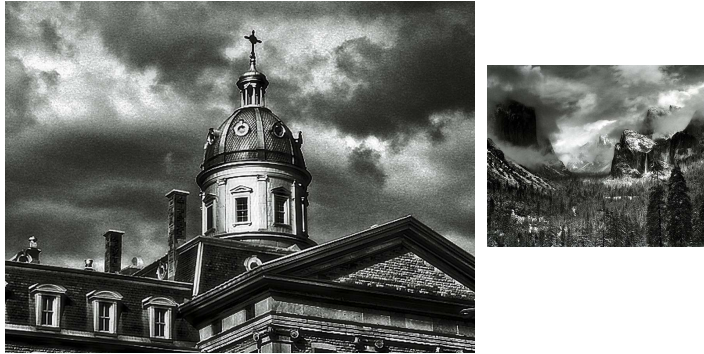
local contrast

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Photographic Style Transfer (cont.)

- Results



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Photographic Style Transfer (cont.)

- Results



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Geometrical Transformations

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Types of Geometrical Transformations

- Scaling
- Translation
- Reflection
- Rotation
- Shearing
- For bitmapped images, we have to **transform every pixel**, and will often require the image to be **resampled**

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Forward Mapping and Inverse Mapping

forward mapping

inverse mapping

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Forward Mapping and Inverse Mapping

$(x', y') = (2x, 2y)$

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Image Scaling

- We will use image scaling as an example
- Assume we want to obtain an image which is s times larger than the original image

forward mapping $(x', y') = (sx, sy)$

inverse mapping $(x, y) = (x'/s, y'/s)$

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Image Scaling (cont.)

- Three strategies to obtain an estimation of X

nearest neighbor
 P_3 is closest
 Use P_3 's pixel value

bilinear interpolation
 $(1-a)(1-b)P_1 + (a)(1-b)P_2 + (1-a)(b)P_3 + (a)(b)P_4$

bicubic interpolation
 using curve to compute weight (nonlinear)

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Image Scaling (cont.)

- Example: scale an image from 160 x 120 to 800 x 600

$(157/5, 123/5) = (31.4, 24.6)$
 $(157, 123)$

$(31, 24)$ P_1 $a = 0.4$ P_2 $(32, 24)$
 $b = 0.6$
 $(31, 25)$ P_3 P_4 $(32, 25)$

nearest neighbor: use color of (31,25)
 bilinear: compute
 $(1-a)(1-b)P_1 + (a)(1-b)P_2 + (1-a)(b)P_3 + (a)(b)P_4$
 0.24 0.16 0.36 0.24

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Image Scaling (cont.)

- Example

nearest neighbor bilinear interpolation bicubic interpolation

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Image Scaling (cont.)

- Example

nearest neighbor bilinear interpolation bicubic interpolation

original x 10

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Image Scaling (cont.)

- Example

original

nearest neighbor bilinear interpolation bicubic interpolation

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Image Scaling (cont.)

- OpenCV

```
void cvResize(  
    const CvArr* src,  
    const CvArr* dst,  
    int interpolation = CV_INTER_LINEAR  
);
```

interpolation can be

CV_INTER_NN, CV_INTER_LINEAR, CV_INTER_CUBIC